

AMCI SV160x2 Sample Program - READ ME

The **AMCI_SV160x2_Basic_Moves_Sample_Program** shows the basic steps needed to begin controlling all of AMCI's integrated servo motor drives. This program will preset the position, make relative and absolute moves, make JOG CW and CCW moves, make CW home move, or clear errors.

This sample program also shows how to read and write data to the drive using SFC14 and SFC15 functions to preserve the consistency of the transferred data.

The following information will help you correctly set the needed parameters for the SFC14 and SFC15 functions.

1. A **SFC14** function is used to read data from the SV160x2 drive. It ensures that consistent data is transferred without any interruption. This instruction has 3 parameters that need to be assigned:
 - a) The **LADDR** parameter selects the PROFINET I/O module from which data will be read. As shown in the Figure 3, the starting address for the SV160x2 input area is 256, which is 100hex.
 - b) The **RECORD** parameter defines the target **Data Block (DB)**, which will contain the Sv160x2 Input Data that is read by this function. Set the pointer to the beginning of the data block (P#DB1.DBX0.0) and define the data length (BYTE 20).
 - c) The **RET_VAL** parameter will contain an error code if an error occurs while the function is being executed.

```
SFC14 function is used to read consistent data from the SV160x2 unit:  
  
LADDR = W#16#100, this is the starting address for the first input Module (256  
= 100hex)  
RECORD = P# DB1.DBX0.0 BYTE 20, pointer loaded with starting bit of the  
Data Block DB1 (byte 0, bit 0) and the length is 20 bytes.  
RET_VAL = MW22 a memory location 1 word long, which is used to store an error  
message if the function is not executed properly  
  
It is this stored data that your ladder logic program should use when  
referencing the SV160x2 unit.
```

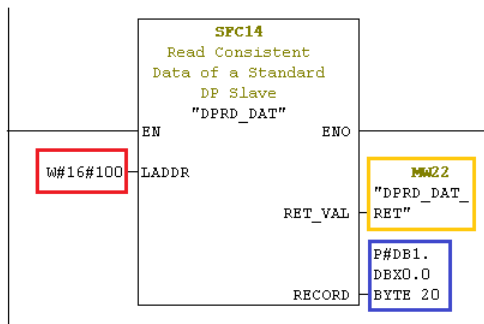


Figure 1: SFC14

2. A **SFC15** function is used to write data to the SV160x2 drive. It ensures that consistent data is transferred without any interruption. This function has 3 parameters that need to be assigned:
 - a) The **LADDR** parameter selects the PROFINET I/O module to which data will be written. As shown in the Figure 3, the starting address for the SV160x2 output area is 256, which is 100hex.
 - b) The **RECORD** parameter defines the target **Data Block (DB)**, which will contain the SV160x2 Output Data to be written to the SV160x2 drive by this function. Set the pointer to the beginning of the data block (P#DB2.DBX0.0) and define the data length (BYTE 20).
 - c) The **RET_VAL** parameter will contain an error code if an error occurs while the function is being executed.

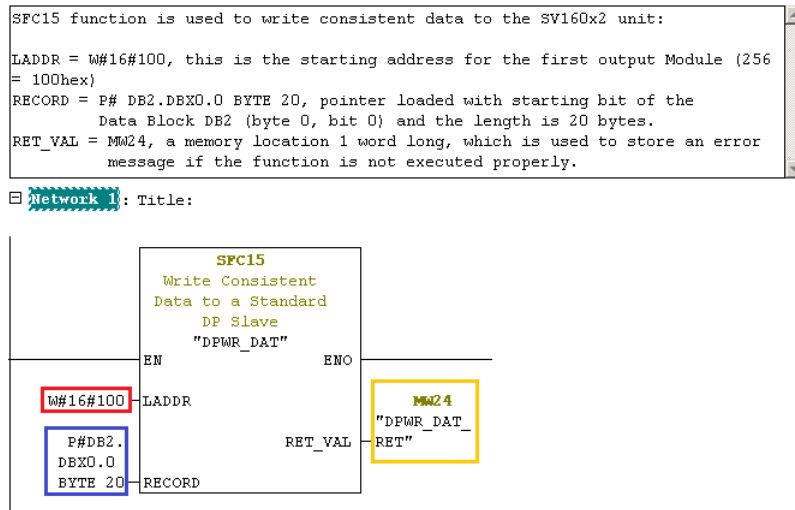


Figure 2: SFC15

ADDITIONAL NOTES

CONFIGURATION GSDML FILES

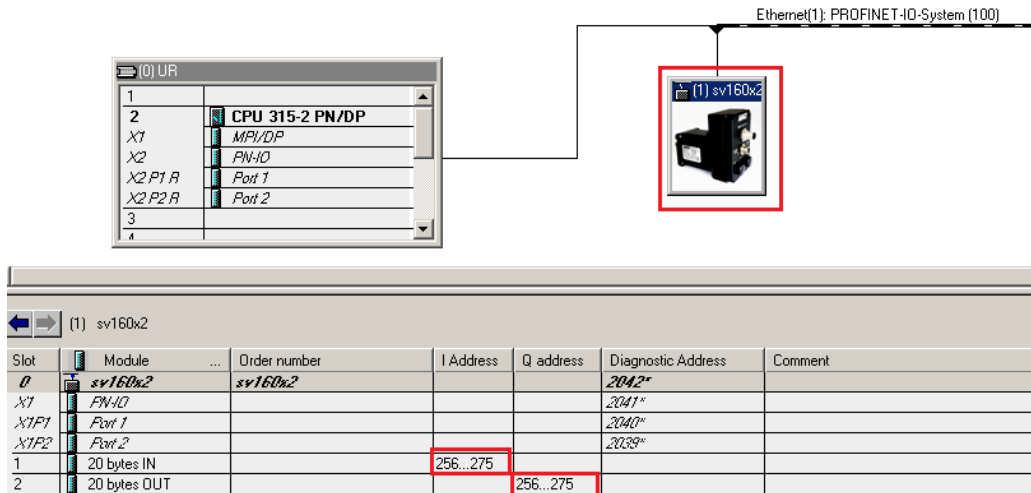
There are two versions, V2.33 and V2.31, of the same GSDML file for all AMCI drives:

- GSDML-V2.33-AMCI-SD-SMD-20171214
- GSDML-V2.31-AMCI-SD-SMD-20171214

If your system does not support the latest version V2.33, try to install an earlier version V2.31.

I/O AREA OF THE SV160x2

After the SV160x2 drive is added to the network configuration, there will be an I/O area assigned to the input and output modules. To determine the range of I/O modules' addresses, go to the HW Configuration window and select the SV160x2. In this example, the address ranges for the SV160x2 are from 256 to 275.



Slot	Module	Order number	I Address	Q address	Diagnostic Address	Comment
0	sv160x2	sv160x2			2042*	
X1	PN-IO				2041*	
X1P1	Port 1				2040*	
X1P2	Port 2				2039*	
1	20 bytes IN		256...275			
2	20 bytes OUT			256...275		

Figure 3: I/O area address range of the SV160x2

CONFIGURATION PARAMETERS

As introduced by the GSDML file, there are configuration parameters that need to be set. To access the configuration parameters, from the HW Configuration window, select the **SV160x2** then right click on the top row – Slot: 0, Module: SV160x2. From the pop-up menu select **Object Properties ...**

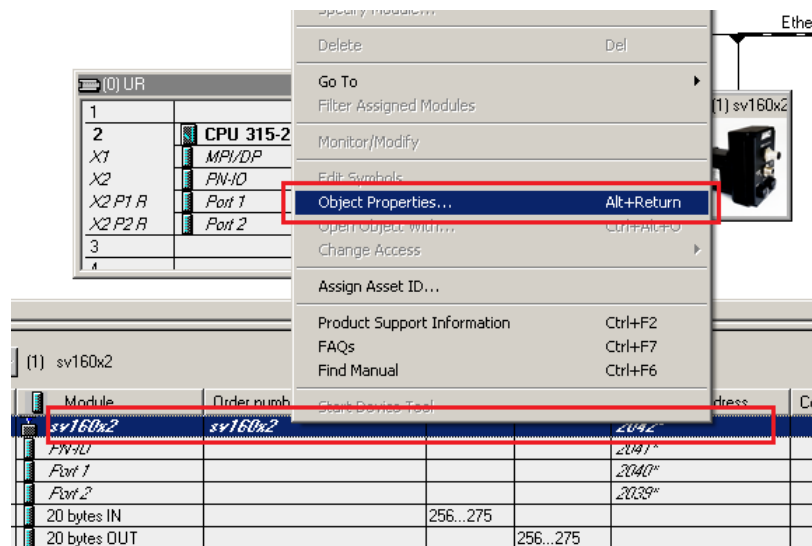


Figure 4: Object Properties

From the pop-up window, select the **Parameters** tab and open the **Configuration Parameters** folder. As you can see in the following figure, there are default values and you can change them for your specific application.

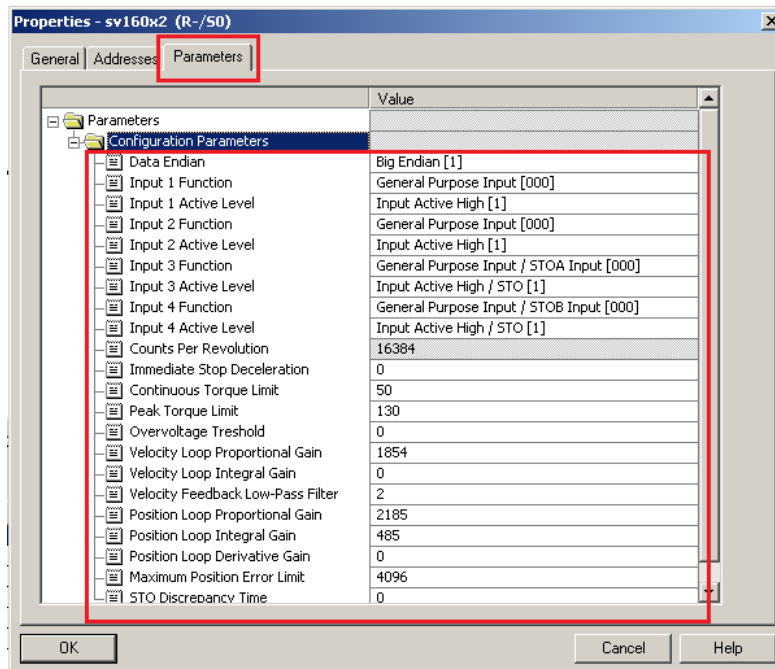


Figure 5: Configuration Parameters

Some of the configuration parameters are selectable from a drop-down menu (like the **Input 1 Function** shown in the following figure) and for others you have to enter a valid value, for example the **Motor Steps Per Turn**.

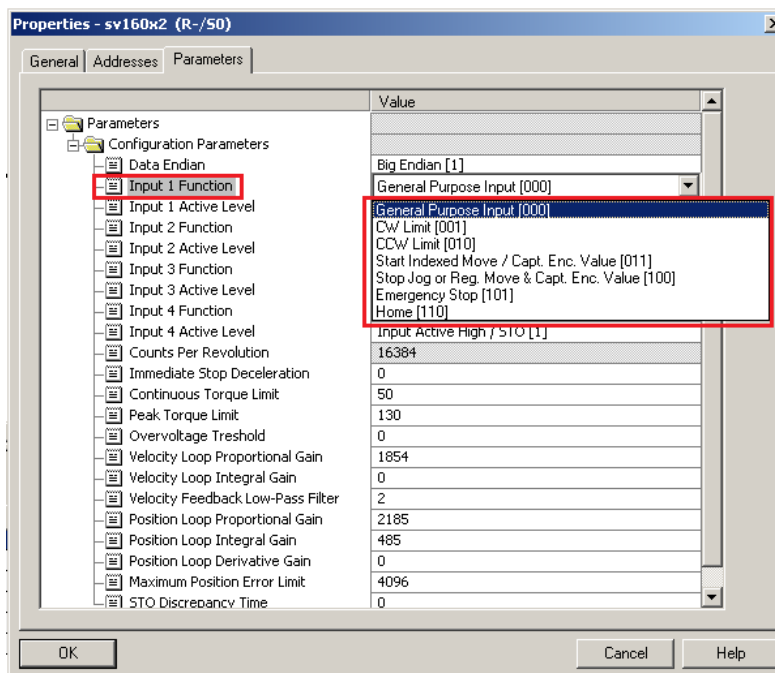


Figure 6: Selectable Configuration Parameters

After all of the Configuration Parameters have been set, save the configuration and download it to the CPU. This configuration data will now automatically be sent to the SV160x2 every time it is powered up.